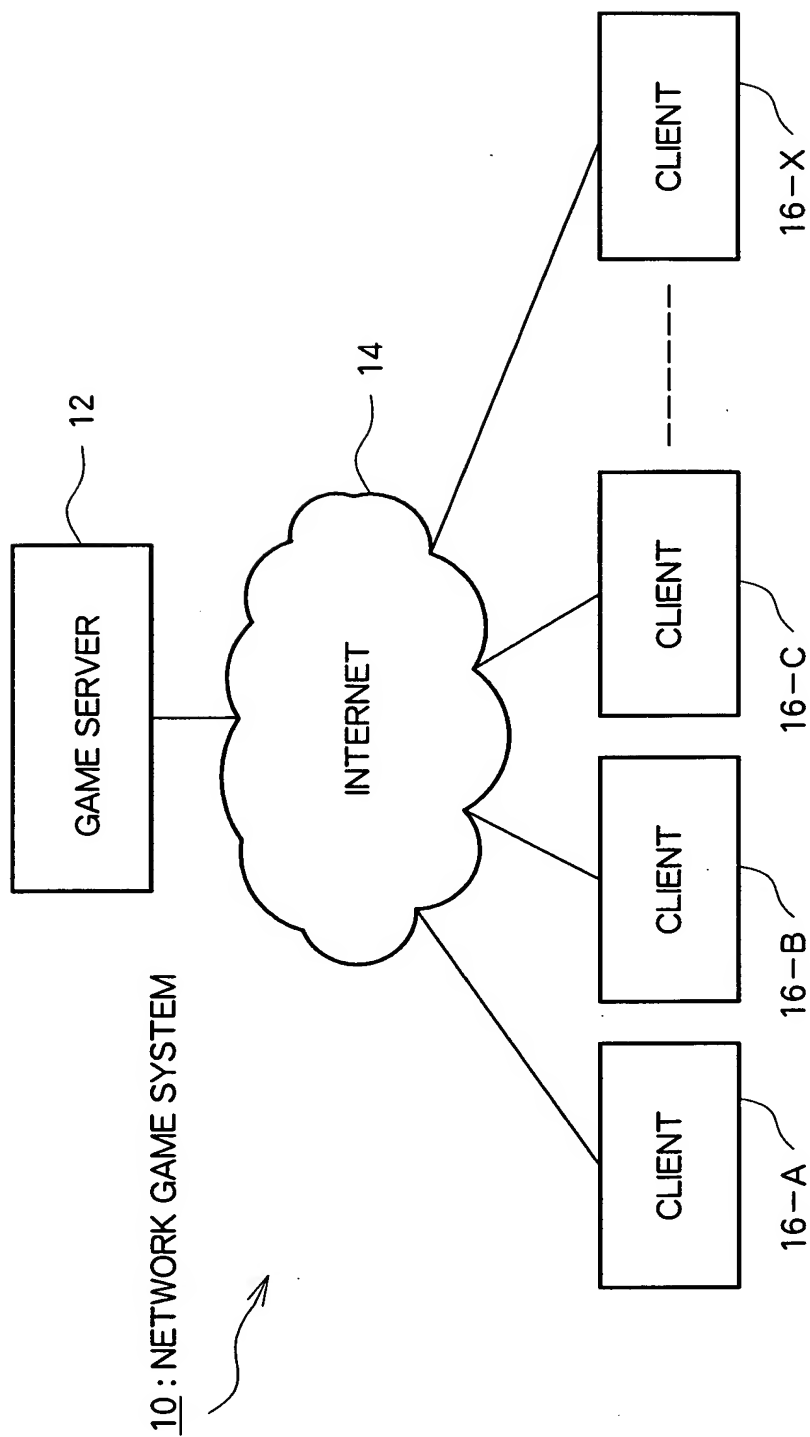


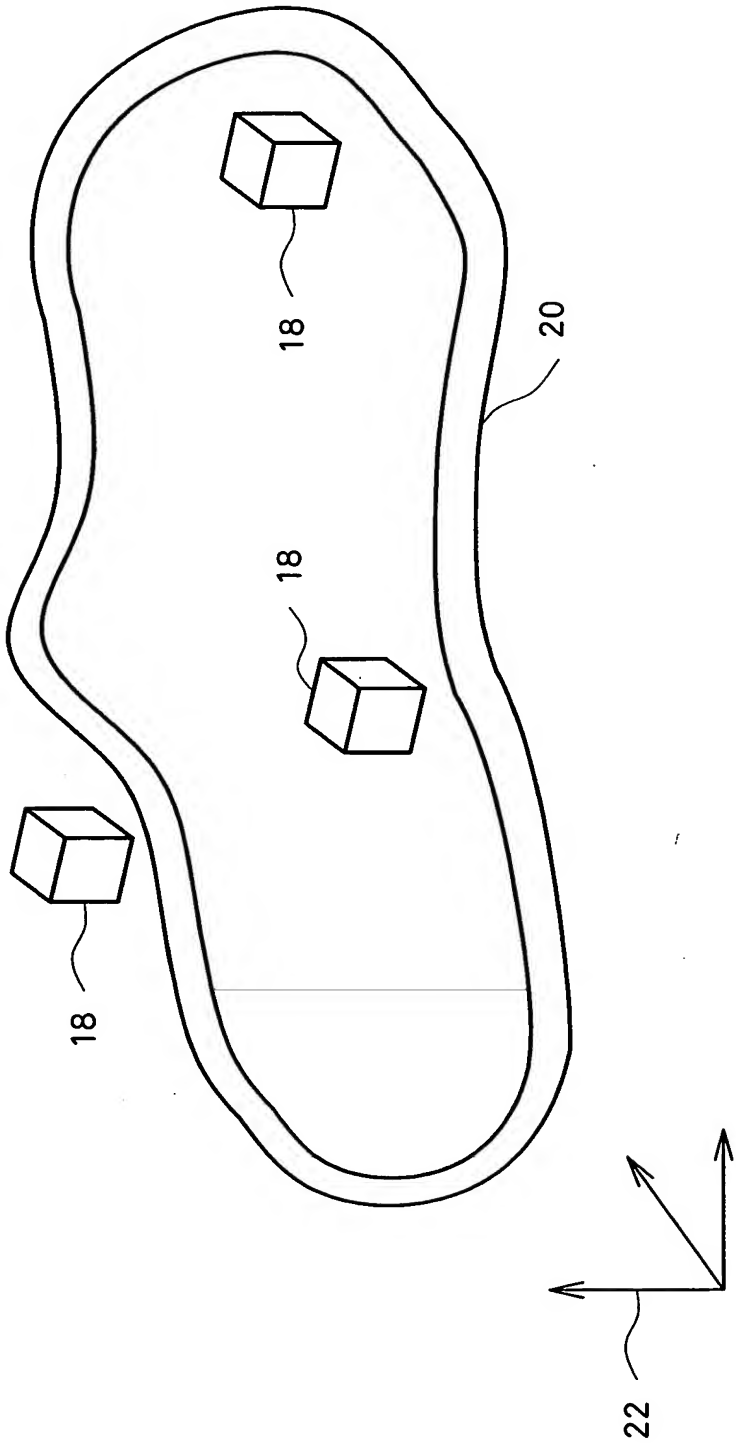
1 / 1 1

FIG. 1



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FIG. 2



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FIG. 3

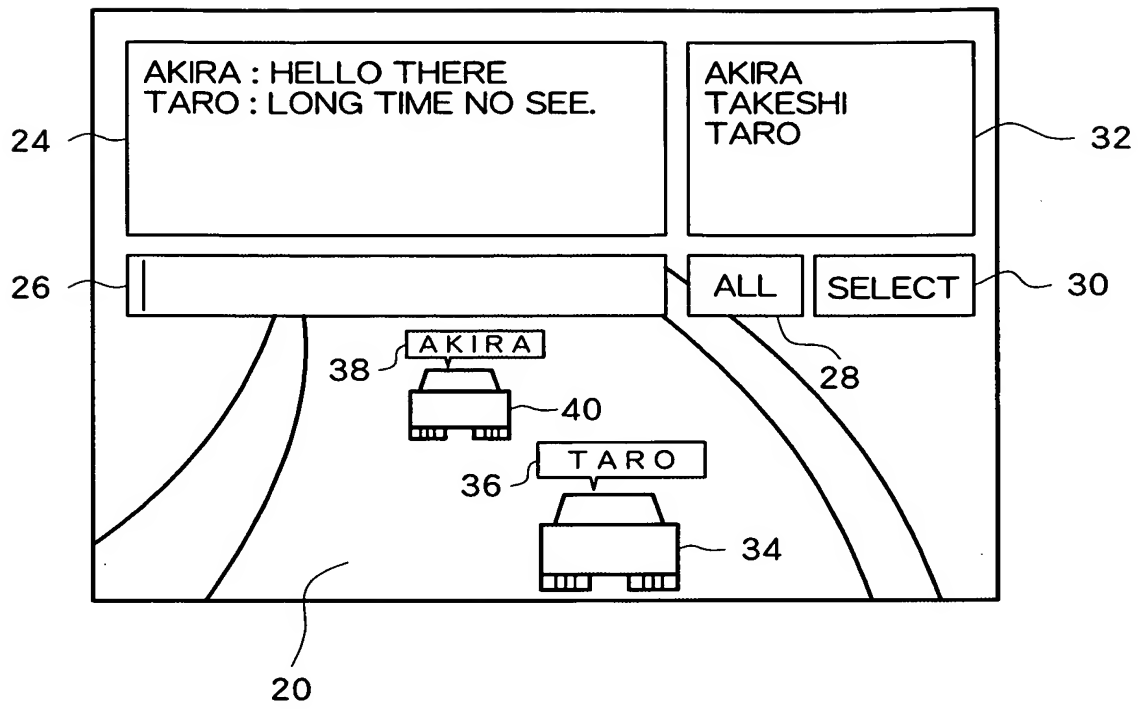
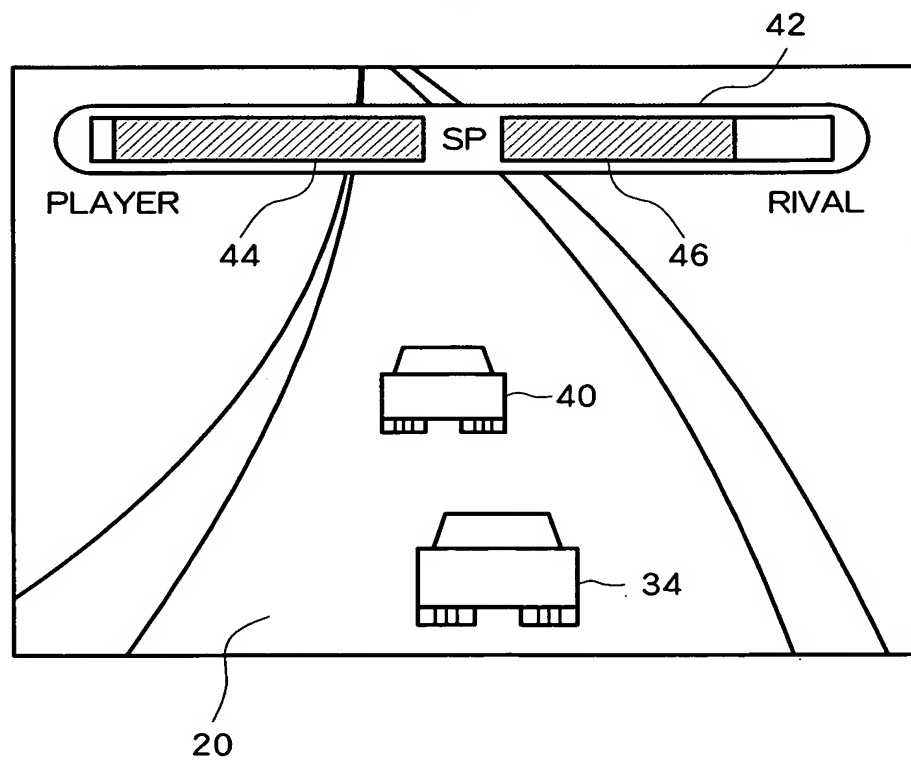
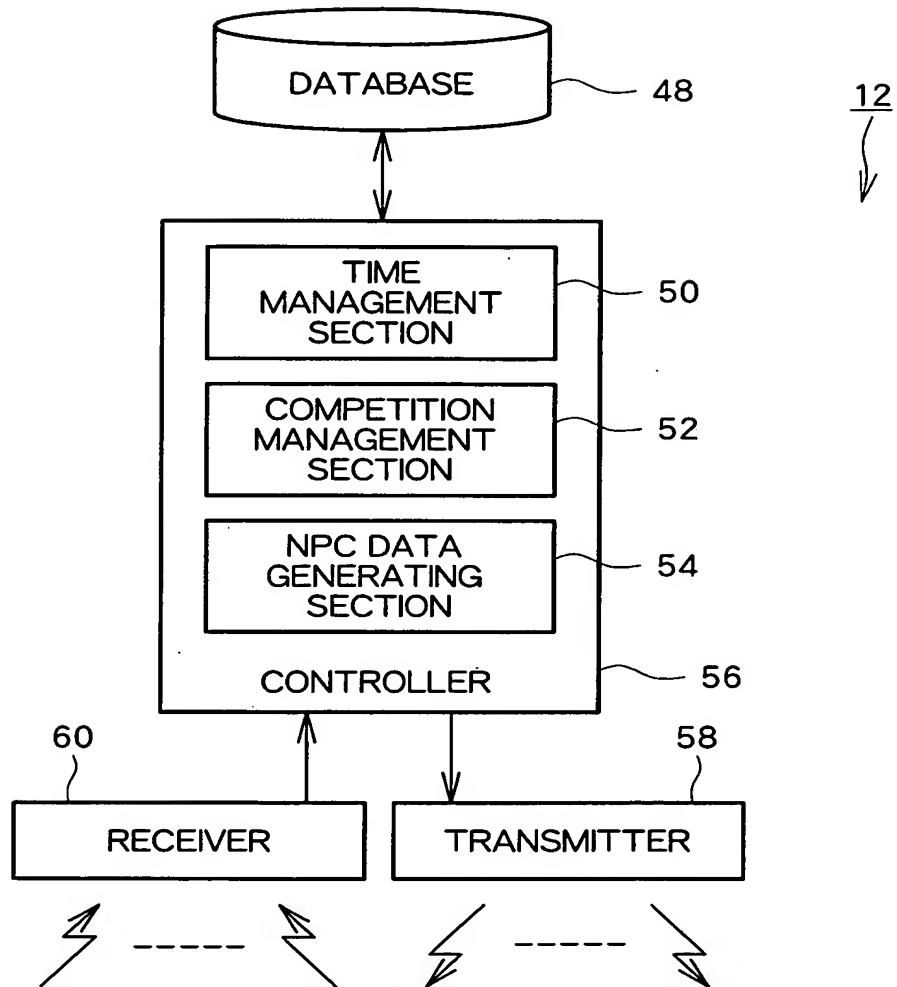


FIG. 4



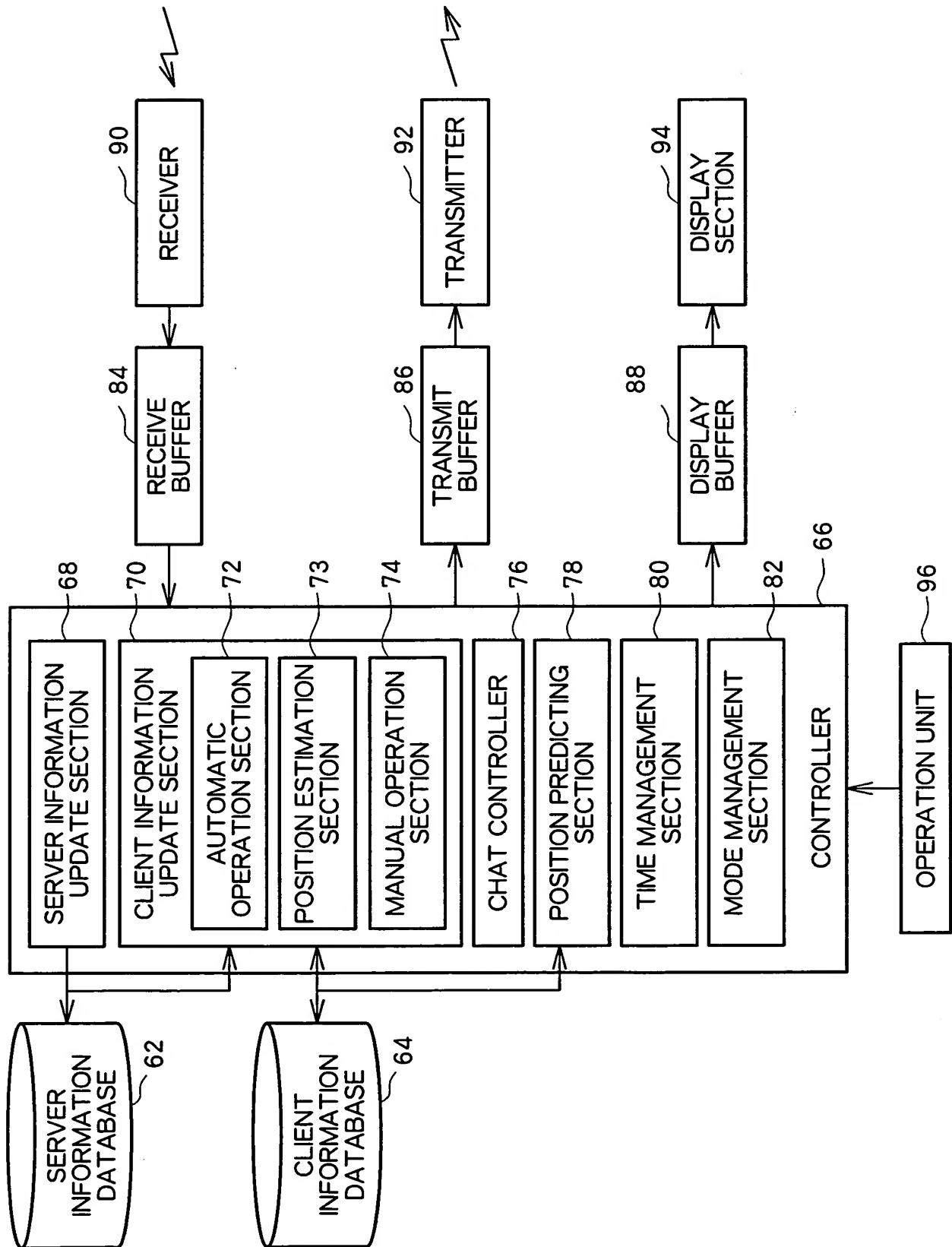
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FIG. 5



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FIG. 6



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FIG. 7

I D	LATEST CURRENT POSITION/TIME	LATEST PREDICTED FUTURE POSITION/TIME	COMPETING FLAG
KEN	PA (KEN) / T (KEN)	PE (KEN) / T (KEN)+ α	1
TARO	PA (TARO) / T (TARO)	PE (TARO) / T (TARO)+ α	1
TAKESHI	PA (TAKESHI) / T (TAKESHI)	PE (TAKESHI) / T (TAKESHI)+ α	0
SNPC1	PA (SNPC1) / T (SNPC1)	PE (SNPC1) / T (SNPC1)+ α	0

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FIG. 8

I D	ADDRESS
AKIRA	x x x. x x x. x x x. x x x
TARO	x x x. x x x. x x x. x x x
KEN	x x x. x x x. x x x. x x x

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FIG. 9

I D	LATEST CURRENT POSITION/TIME	LATEST PREDICTED FUTURE POSITION/TIME
KEN	PA (KEN) / T (KEN)	PE (KEN) / T (KEN) + α
TARO	PA (TARO) / T (TARO)	PE (TARO) / T (TARO) + α
CNPCKEN1	PA (CNPCKEN1) / T (CNPCKEN1)	PE (CNPCKEN1) / T (CNPCKEN1) + α
CNPCTARO1	PA (CNPCTARO1) / T (CNPCTARO1)	PE (CNPCTARO1) / T (CNPCTARO1) + α

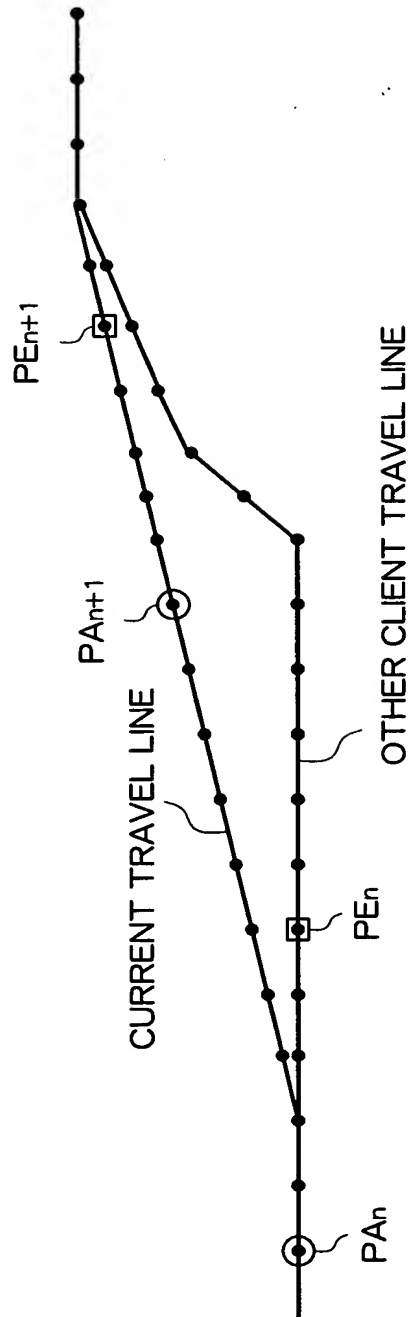
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FIG.10

I D	CURRENT POSITION	CURRENT ATTITUDE	CURRENT SPEED VECTOR
KEN	PA (KEN)	BA (KEN)	VA (KEN)
TARO	PA (TARO)	BA (TARO)	VA (TARO)
TAKESHI	PA (TAKESHI)	BA (TAKESHI)	VA (TAKESHI)
SNPC1	PA (SNPC1)	BA (SNPC1)	VA (SNPC1)

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FIG. 11



1 1 / 1 1

FIG. 12

